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 Inventor(s): Olivier Giaume *et al.*  
 Method for Optimization of Temporal Performances with Rapid Convergence  
 REPLACEMENT DRAWING SHEET

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$C_k$  

$C_i$ (Initial Cell) $C_k$ (Replacement Cell)	$C_0$	$C_1$	$C_2$	$C_3$
$C_0$	X	val <sub>1</sub>	val <sub>2</sub>	val <sub>3</sub>
$C_1$	X	X	val <sub>1</sub>	val <sub>2</sub>
$C_2$	X	X	X	val <sub>1</sub>
$C_3$	X	X	X	X

$C_i$	val <sub>i</sub>
$C_0$	val <sub>0</sub>
$C_1$	val <sub>1</sub>
$C_2$	val <sub>2</sub>
$C_3$	val <sub>3</sub>
$C_4$	val <sub>4</sub>
$C_5$	val <sub>5</sub>
$C_6$	val <sub>6</sub>
$C_7$	val <sub>7</sub>

FIG. 4